

12-OUTPUT DIFFERENTIAL Z-BUFFER FOR PCIE GEN3 AND OPI

9ZX21200

Description

The 9ZX21200 is a small-footprint 12-output differential buffer that meets all the performance requirements of the Intel DB1200Z specification. The 9ZX21200 is backwards compatible to PCIe Gen1 and Gen2 applications. A fixed, internal feedback path maintains low drift for critical QPI applications. In bypass mode, the 9ZX21200 can provide outputs up to 150MHz.

Recommended Application

12-output PCIe Gen3/ QPI differential buffer for Romley and newer platforms

Key Specifications

- Cycle-to-cycle jitter <50ps
- Output-to-output skew < 65 ps
- Input-to-output delay variation <50ps
- PCle Gen3 phase jitter < 1.0ps RMS
- QPI 9.6GT/s 12UI phase jitter < 0.2ps RMS

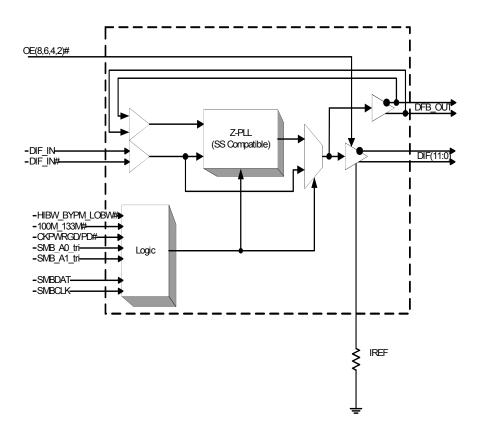
Features/Benefits

- Space-saving 56-pin package
- · Fixed feedback path for 0ps input-to-output delay
- 9 Selectable SMBus Addresses; Mulitple devices can share the same SMBus Segment
- 4 OE# pins; Hardware control of four outputs
- PLL or bypass mode; PLL can dejitter incoming clock
- 100MHz or 133MHz PLL mode operation; supports PCle and QPI applications
- Selectable PLL bandwidth; minimizes jitter peaking in downstream PLL's
- Spread Spectrum Compatible; tracks spreading input clock for low EMI
- Software control of PLL Bandwidth and Bypass Settings/PLL can dejitter incoming clock (B Rev only)

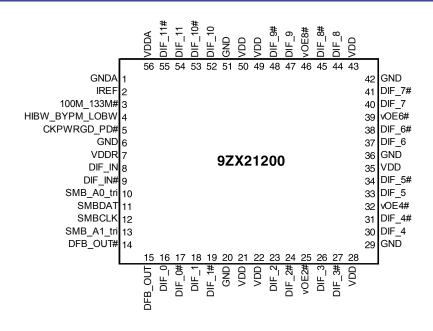
Output Features

• 12 - 0.7V differential HCSL output pairs

Block Diagram







Notes: Pins with ^ prefix have internal 120K pullup
Pins with v prefix have internal 120K pulldown.
Even though the feedback path is fixed, the DFB_OUT
pair still needs a termination network for the part to
function.

Power Management Table

CKPWRGD_PD#	DIF_IN/ DIF_IN#	SMBus EN bit	DIF(11:0)/ DIF(11:0)#	PLL STATE IF NOT IN BYPASS MODE
0	X	Х	Low/Low	OFF
4	Running	0	Low/Low	ON
l '	running	1	Running	ON

MLF Power Connections

	Pin Number		
VDD	VDD	GND	Description
56		1	Analog PLL
7		6	Analog Input
21,35,50	22,28,43,49	20,29,36,42, 51	DIF clocks

Functionality at Power-up (PLL mode)

100M_133M#	DIF_IN MHz	DIF(11:0)		
1	100.00	DIF_IN		
0	133.33	DIF_IN		

PLL Operating Mode Readback Table

HiBW_BypM_LoBW#	Byte0, bit 7	Byte 0, bit 6
Low (Low BW)	0	0
Mid (Bypass)	0	1
High (High BW)	1	1

PLL Operating Mode Table

HiBW_BypM_LoBW#	MODE
Low	PLL Lo BW
Mid	Bypass
High	PLL Hi BW

NOTE: PLL is OFF in Bypass Mode

Tri-Level Input Thresholds

Level	Voltage
Low	<0.8V
Mid	1.2 <vin<1.8v< td=""></vin<1.8v<>
High	Vin > 2.2V

9ZX21200 SMBus Addressing

Pi	n	
SMB_A1_tri	SMB_A0_tri	SMBus Address
0	0	D8
0	М	DA
0	1	DE
M	0	C2
М	М	C4
М	1	C6
1	0	CA
1	М	CC
1	1	CE



	-		
PIN #		TYPE	DESCRIPTION
1	GNDA	PWR	Ground pin for the PLL core.
	ID EE	OUT.	This pin establishes the reference for the differential current-mode output pairs. It requires a fixed precision
2	IREF	OUT	resistor to ground. 4750hm is the standard value for 1000hm differential impedance. Other impedances
			require different values. See data sheet. 3.3V Input to select operating frequency
3	100M_133M#	IN	See Functionality Table for Definition
			Trilevel input to select High BW, Bypass or Low BW mode.
4	HIBW_BYPM_LOBW#	IN	See PLL Operating Mode Table for Details.
	OVENUE OF THE		Notifies device to sample latched inputs and start up on first high assertion, or exit Power Down Mode on
5	CKPWRGD_PD#	IN	subsequent assertions. Low enters Power Down Mode.
6	GND	PWR	Ground pin.
7	VDDR	PWR	3.3V power for differential input clock (receiver). This VDD should be treated as an analog power rail and
			filtered appropriately.
8	DIF_IN	IN	0.7 V Differential TRUE input
9	DIF_IN#	IN	0.7 V Differential Complementary Input
10	SMB_A0_tri	IN	SMBus address bit. This is a tri-level input that works in conjunction with the SMB_A1 to decode 1 of 9
11	SMBDAT	1/0	SMBus Addresses. Data pin of SMBUS circuitry, 5V tolerant
12	SMBCLK	IN	Clock pin of SMBUS circuitry, 5V tolerant
			SMBus address bit. This is a tri-level input that works in conjunction with the SMB_A0 to decode 1 of 9
13	SMB_A1_tri	IN	SMBus Addresses.
	DED 01:-::	<u> </u>	Complementary half of differential feedback output, provides feedback signal to the PLL for synchronization
14	DFB_OUT#	OUT	with input clock to eliminate phase error.
15	DFB_OUT	OUT	True half of differential feedback output, provides feedback signal to the PLL for synchronization with the input
			clock to eliminate phase error.
	DIF_0		0.7V differential true clock output
	DIF_0#		0.7V differential Complementary clock output
	DIF_1		0.7V differential true clock output
_	DIF_1#		0.7V differential Complementary clock output
20	GND		Ground pin.
21 22	VDD VDD		Power supply, nominal 3.3V Power supply, nominal 3.3V
	DIF_2		0.7V differential true clock output
	DIF_2#		0.7V differential Complementary clock output
			Active low input for enabling DIF pair 2.
25	vOE2#	IN	1 =disable outputs, 0 = enable outputs
26	DIF_3	OUT	0.7V differential true clock output
	DIF_3#	OUT	0.7V differential Complementary clock output
28	VDD	PWR	Power supply, nominal 3.3V
29	GND	PWR	Ground pin.
	DIF_4		0.7V differential true clock output
31	DIF_4#	OUT	0.7V differential Complementary clock output
32	vOE4#	IN	Active low input for enabling DIF pair 4
	DIE	OUT	1 =disable outputs, 0 = enable outputs 0.7V differential true clock output
	DIF_5 DIF_5#		
	VDD		0.7V differential Complementary clock output Power supply, nominal 3.3V
	GND		Ground pin.
	DIF_6		0.7V differential true clock output
	DIF_6#		0.7V differential Complementary clock output
		i e	Active low input for enabling DIF pair 6.
	vOE6#	IN	1 =disable outputs, 0 = enable outputs
	DIF_7		0.7V differential true clock output
41	DIF_7#		0.7V differential Complementary clock output
	GND		Ground pin.
	VDD		Power supply, nominal 3.3V
44	DIF_8		0.7V differential true clock output
45	DIF_8#		0.7V differential Complementary clock output
46	vOE8#	IN	Active low input for enabling DIF pair 8.
		OUT	1 =disable outputs, 0 = enable outputs 0.7V differential true clock output
	DIF_9 DIF_9#		0.7V differential true clock output 0.7V differential Complementary clock output
	VDD		Power supply, nominal 3.3V
	VDD		Power supply, nominal 3.3V
	GND		Ground pin.
	DIF_10		0.7V differential true clock output
	DIF_10#		0.7V differential Complementary clock output
	 DIF_11		0.7V differential true clock output
55	DIF_11#		0.7V differential Complementary clock output
56	VDDA	PWR	3.3V power for the PLL core.



Stresses above the ratings listed below can cause permanent damage to the 9ZX21200. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
3.3V Core Supply Voltage	VDD, VDDA	VDD for core logic and PLL			4.6	V	1,2
IO Supply Voltage	VDD	VDD for differential IO			4.6	V	1,2
Input Low Voltage	V_{IL}		GND-0.5			V	1
Input High Voltage	V_{IH}	Except for SMBus interface			$V_{DD} + 0.5V$	V	1
Input High Voltage	V _{IHSMB}	SMBus clock and data pins			5.5V	V	1
Storage Temperature	Ts		-65		150	, C	1
Junction Temperature	Tj				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Clock Input Parameters

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V} + /-5\%$

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V_{IHDIF}	Differential inputs (single-ended measurement)	600	800	1150	mV	1
Input Low Voltage - DIF_IN	V _{IL DIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1
Input Common Mode Voltage - DIF_IN	V _{COM}	Common Mode Input Voltage	300		1000	mV	1
Input Amplitude - DIF_IN	V_{SWING}	Peak to Peak value	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4		8	V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	1
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45		55	%	1
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		125	ps	1

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²Operation under these conditions is neither implied nor guaranteed.

²Slew rate measured through +/-75mV window centered around differential zero



 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V } +/-5\%$

$T_A = T_{COM}$; Supply Voltage V	$_{DD} = 3.3 \text{ V} +$	-/-5%				1	
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Ambient Operating Temperature	T _{COM}	Commmercial range	0		70	°C	1
Input High Voltage	V_{IH}	Single-ended inputs, except SMBus, low threshold and tri-level inputs	2		V _{DD} + 0.3	٧	1
Input Low Voltage	V_{IL}	Single-ended inputs, except SMBus, low threshold and tri-level inputs	GND - 0.3		0.8	٧	1
	I _{IN}	Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$	-5		5	uA	1
Input Current	I _{INP}	Single-ended inputs $V_{\text{IN}}=0$ V; Inputs with internal pull-up resistors $V_{\text{IN}}=$ VDD; Inputs with internal pull-down resistors	-200		200	uA	1
	F_{ibyp}	V _{DD} = 3.3 V, Bypass mode	33		150	MHz	2
Input Frequency	F_{ipll}	$V_{DD} = 3.3 \text{ V}, 100\text{MHz PLL mode}$	90	100.00	110	MHz	2
	F_{ipll}	$V_{DD} = 3.3 \text{ V}, 133.33 \text{MHz PLL mode}$	120	133.33	147	MHz	2
Pin Inductance	L_{pin}				7	nΗ	1
	C_{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	C _{INDIF_IN}	DIF_IN differential clock inputs	1.5		2.7	рF	1,4
	C_{OUT}	Output pin capacitance			6	рF	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock		0.300	1	ms	1,2
Input SS Modulation Frequency	f _{MODIN}	Allowable Frequency (Triangular Modulation)	30		33	kHz	1
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	4		12	clocks	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion		16	300	us	1,3
Tfall	t _F	Fall time of control inputs			10	ns	1,2
Trise	t _R	Rise time of control inputs			10	ns	1,2
SMBus Input Low Voltage	V_{ILSMB}				0.8	V	1
SMBus Input High Voltage	V_{IHSMB}		2.1		V_{DDSMB}	V	1
SMBus Output Low Voltage	V_{OLSMB}	@ I _{PULLUP}			0.4	٧	1
SMBus Sink Current	I _{PULLUP}	@ V _{OL}	4			mA	1
Nominal Bus Voltage	V_{DDSMB}	3V to 5V +/- 10%	2.7		5.5	V	1
SCLK/SDATA Rise Time	t _{RSMB}	(Max VIL - 0.15) to (Min VIH + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t _{FSMB}	(Min VIH + 0.15) to (Max VIL - 0.15)			300	ns	1
SMBus Operating Frequency	f _{MAXSMB}	Maximum SMBus operating frequency			100	kHz	1,5

¹Guaranteed by design and characterization, not 100% tested in production.

 $^{^2\}mbox{Control}$ input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

⁴DIF_IN input

⁵The differential input clock must be running for the SMBus to be active



 $T_A = T_{COM}$; Supply Voltage VDD = 3.3 V +/-5%

<u> </u>							
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	Trf	Scope averaging on	1	2	4	V/ns	1, 2, 3
Slew rate matching	ΔTrf	Slew rate matching, Scope averaging on		8	20	%	1, 2, 4
Voltage High	VHigh	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	660	705	850	mV	1
Voltage Low	VLow	averaging on)	-150	1	150	1117	1
Max Voltage	Vmax	Measurement on single ended signal using		725	1150	mV	1
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	-22] IIIV	1
Vswing	Vswing	Scope averaging off	300	1407		mV	1, 2
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	309	550	mV	1, 5
Crossing Voltage (var)	Δ-Vcross	Scope averaging off		22	140	mV	1, 6

¹Guaranteed by design and characterization, not 100% tested in production. IREF = VDD/(3xR_R). For R_R = 412Ω (1%), I_{REF} = 2.7mA. I_{OH} = 6.4 x I_{REF} and V_{OH} = 0.7V @ Z_O =85Ω differential impedance.

Electrical Characteristics-Current Consumption

 $T_A = T_{COM}$: Supply Voltage VDD = 3.3 V +/-5%

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Operating Current	I _{DDVDD}	133MHz, C_L = Full load; VDD rail, $Zo=85\Omega$		260	275	mA	1
	I _{DDVDDA}	133MHz, C_L = Full load; VDD rail, Zo=85 Ω		13	20	mA	1
Davis and assure Ossessant	I _{DDVDDPD}	Power Down, VDD rail, Zo=85Ω		2	6	mA	1
Powerdown Current	I _{DDVDDAPD}	Power Down, VDD rail, Zo=85Ω		1.3	2	mA	1

¹Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate of Clock / falling edge rate of Clock#. It is measured in a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope uses for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of V_cross_min/max (V_cross absolute) allowed. The intent is to limit Vcross induced modulation by setting V_cross_delta to be smaller than V_cross absolute.



 $T_A = T_{COM}$: Supply Voltage VDD = 3.3 V +/-5%

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
CLK_IN, DIF[x:0]	t _{SPO_PLL}	Input-to-Output Skew in PLL mode nominal value @ 25°C, 3.3V	-100	29	100	ps	1,2,4,5,8
CLK_IN, DIF[x:0]	t _{PD_BYP}	Input-to-Output Skew in Bypass mode nominal value @ 25°C, 3.3V	2.5	3.7	4.5	ns	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSPO_PLL}	Input-to-Output Skew Varation in PLL mode across voltage and temperature	-50		50	ps	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSPO_BYP}	Input-to-Output Skew Varation in Bypass mode across voltage and temperature	-250		250	ps	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DTE}	Random Differential Tracking error beween two 9ZX devices in Hi BW Mode		2.9	5	ps (rms)	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSSTE}	Random Differential Spread Spectrum Tracking error beween two 9ZX devices in Hi BW Mode		14	75	ps	1,2,3,5,8
DIF{x:0]	t _{SKEW_ALL}	Output-to-Output Skew across all outputs (Common to Bypass and PLL mode)		32	65	ps	1,2,3,8
PLL Jitter Peaking	jpeak-hibw	LOBW#_BYPASS_HIBW = 1	0	1.8	2.5	dB	7,8
PLL Jitter Peaking	j _{peak-lobw}	LOBW#_BYPASS_HIBW = 0	0	0.7	2	dB	7,8
PLL Bandwidth	pll _{HIBW}	LOBW#_BYPASS_HIBW = 1	2	3.1	4	MHz	8,9
PLL Bandwidth	pll _{LOBW}	LOBW#_BYPASS_HIBW = 0	0.7	1.1	1.4	MHz	8,9
Duty Cycle	t _{DC}	Measured differentially, PLL Mode	45	49.6	55	%	1
Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz	-2	-0.2	2	%	1,10
Jitter, Cycle to cycle	t:	PLL mode		15.7	50	ps	1,11
Cittor, Cycle to cycle	T _{jcyc-cyc}	Additive Jitter in Bypass Mode		0.1	50	ps	1,11

Notes for preceding table:

¹ Measured into fixed 2 pF load cap. Input to output skew is measured at the first output edge following the corresponding input.

² Measured from differential cross-point to differential cross-point. This parameter can be tuned with external feedback path, if present.

³ All Bypass Mode Input-to-Output specs refer to the timing between an input edge and the specific output edge created by it.

⁴ This parameter is deterministic for a given device

⁵ Measured with scope averaging on to find mean value.

^{6.} t is the period of the input clock

⁷ Measured as maximum pass band gain. At frequencies within the loop BW, highest point of magnification is called PLL jitter peaking.

^{8.} Guaranteed by design and characterization, not 100% tested in production.

⁹ Measured at 3 db down or half power point.

¹⁰ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

¹¹ Measured from differential waveform



 $T_A = T_{COM}$: Supply Voltage VDD = 3.3 V +/-5%

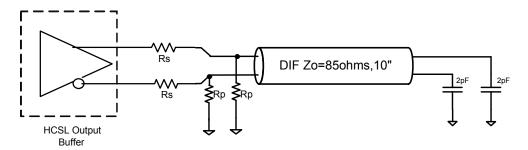
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	Notes
	t _{jphPCleG1}	PCIe Gen 1		32	86	ps (p-p)	1,2,3
	t	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.8	3	ps (rms)	1,2
	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		1.9	3.1	ps (rms)	1,2
Phase Jitter, PLL Mode	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz)		0.45	1	ps (rms)	1,2,4
		QPI & SMI (100MHz or 133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.20	0.5	ps (rms)	1,5
	t _{jphQPI_} SMI	QPI & SMI (100MHz, 8.0Gb/s, 12UI)		0.14	0.3	ps (rms)	1,5
		QPI & SMI (100MHz, 9.6Gb/s, 12UI)		0.12	0.2	ps (rms)	1,5
	t _{jphPCleG1}	PCIe Gen 1		0.10	10	ps (p-p)	1,2,3
	t _{jphPCleG2}	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.13	0.1	ps (rms)	1,2,6
		PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.10	0.5	ps (rms)	1,2,6
Additive Phase Jitter, Bypass mode	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz)		0.10	0.2	ps (rms)	1,2,4,6
Буразз пюсс		QPI & SMI (100MHz or 133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.09	0.1	ps (rms)	1,5,6
	t _{jphQPI_} SMI	QPI & SMI (100MHz, 8.0Gb/s, 12UI)		0.09	0.1	ps (rms)	1,5,6
		QPI & SMI (100MHz, 9.6Gb/s, 12UI)		0.09	0.1	ps (rms)	1,5,6

¹ Applies to all outputs.

Differential Output Terminations

DIF Zo (Ω)	Iref (Ω)	Rs (Ω)	Rp (Ω)
100	475	33	50
85	412	27	42.2 or 43.2

9ZX21200 Differential Test Loads



² See http://www.pcisig.com for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

⁴ Subject to final radification by PCI SIG.

⁵ Calculated from Intel-supplied Clock Jitter Tool v 1.6.4

⁶ For RMS figures, additive jitter is calculated by solving the following equation: (Additive jitter)² = (total jitter)² - (input jitter)²



		Measurement Window								
	Center	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
SSC OFF	Freq. MHz	-c2c jitter Abs Per Min	-SSC Short-Term Average Min	- ppm Long-Term Average Min	0 ppm Period Nominal	+ ppm Long-Term Average Max	+SSC Short-Term Average Max	+c2c jitter AbsPer Max	Units	Notes
DIF	100.00	9.94900		9.99900	10.00000	10.00100		10.05100	ns	1,2,3
DII	133.33	7.44925		7.49925	7.50000	7.50075		7.55075	ns	1,2,4

Clock Periods-Differential Outputs with Spread Spectrum Enabled

			Measurement Window								
		1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock			
	SSC ON	Center Freq. MHz	-c2c jitter AbsPer Min	-SSC Short-Term Average Min	- ppm Long-Term Average Min	0 ppm Period Nominal	+ ppm Long-Term Average Max	+SSC Short-Term Average Max	+c2c jitter AbsPer Max	Units	Notes
	DIF	99.75	9.94906	9.99906	10.02406	10.02506	10.02607	10.05107	10.10107	ns	1,2,3
	DIF	133.00	7.44930	7.49930	7.51805	7.51880	7.51955	7.53830	7.58830	ns	1,2,4

Notes:

9ZX21200

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² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK420BQ/CK410B+ accuracy requirements (+/-100ppm). The 9ZX21200 itself does not contribute to ppm error.

³ Driven by SRC output of main clock, 100 MHz PLL Mode or Bypass mode

⁴ Driven by CPU output of main clock, 133 MHz PLL Mode or Bypass mode



How to Write

- · Controller (host) sends a start bit
- · Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

	Index Bl	ock '	Write Operation
Controll	er (Host)		IDT (Slave/Receiver)
Т	starT bit		
Slave A	Slave Address		
WR	WRite		
			ACK
Beginning	g Byte = N		
			ACK
Data Byte	Count = X		
			ACK
Beginnin	g Byte N		
			ACK
0		$\rfloor \times \vert$	
0		X Byte	0
0		(a)	0
			0
Byte N	Byte N + X - 1		
			ACK
Р	stoP bit		

How to Read

- · Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- · Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- · Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

	Index Block Read Operation							
Cor	ntroller (Host)		IDT (Slave/Receiver)					
Т	starT bit							
SI	ave Address							
WR	WRite							
			ACK					
Begi	nning Byte = N							
			ACK					
RT	Repeat starT							
SI	ave Address							
RD	ReaD							
			ACK					
			Data Byte Count=X					
	ACK							
			Beginning Byte N					
	ACK							
		e)	0					
	0	X Byte	0					
	0	×	0					
	0							
			Byte N + X - 1					
N	Not acknowledge							
Р	stoP bit							



Byte	e 0 Pin#	# Name	Control Function	Type	0	1	Default		
Bit 7	3	PLL Mode 1	PLL Operating Mode Rd back 1	R	See PLL Op	Latch			
Bit 6	3	PLL Mode 0	PLL Operating Mode Rd back 0	R	Readba	Latch			
Bit 5			Reserved						
Bit 4			Reserved						
Bit 3	These bits	s PLL_SW_EN	Enable S/W control of PLL BW	RW	HW Latch	S/W Control	0		
Bit 2	available in B	B PLL Mode 1	PLL Operating Mode 1	RW	See PLL Op	erating Mode	1		
Bit 1	rev only.	PLL Mode 0	0 PLL Operating Mode 1 RW Readback Table				1		
Bit 0	2	100M 133M#	Frequency Select Readback R 13		133MHz	100MHz	Latch		

SMBusTable: Output Control Register

Byte	Byte 1 Pin # Name		Control Function	Type	0	1	Default
Bit 7	42/41	DIF_7_En	Output Control overrides OE# pin	RW			1
Bit 6	38/37	DIF_6_En	Output Control overrides OE# pin	RW			1
Bit 5	34/35	DIF_5_En	Output Control overrides OE# pin	RW		Enable	1
Bit 4	30/29	DIF_4_En	Output Control overrides OE# pin	RW	Low/Low		1
Bit 3	25/26	DIF_3_En	Output Control	RW	LOW/LOW		1
Bit 2	23/24	DIF_2_En	Output Control	RW			1
Bit 1	18/19	DIF_1_En	Output Control	RW			1
Bit 0	16/17	DIF_0_En	Output Control	RW			1

SMBusTable: Output Control Register

Byte	2 Pin#	Name	Control Function	Type	0	1	Default		
Bit 7			Reserved						
Bit 6			Reserved						
Bit 5			Reserved						
Bit 4			Reserved						
Bit 3	55/54	DIF_11_En	Output Control	RW		Enable	1		
Bit 2	53/52	DIF_10_En	Output Control	RW	Low/Low		1		
Bit 1	48/47	DIF_9_En	Output Control	RW	Low/Low		1		
Bit 0	46/45	DIF_8_En	Output Control	RW		1			

SMBusTable: Reserved Register

Byte 3	Pin #	Name	Control Function	Type	0	1	Default
Bit 7			Reserved				0
Bit 6		Reserved				0	
Bit 5		Reserved				0	
Bit 4		Reserved				0	
Bit 3			Reserved				0
Bit 2			Reserved				0
Bit 1		Reserved				0	
Bit 0		Reserved				0	

SMBusTable: Reserved Register

Byte	2 4	Pin #	Name	Control Function		0	1	Default
Bit 7				Reserved				0
Bit 6			Reserved				0	
Bit 5			Reserved					0
Bit 4			Reserved				0	
Bit 3				Reserved				0
Bit 2			Reserved				0	
Bit 1			Reserved				0	
Bit 0			Reserved				0	



SMBusTable: Vendor & Revision ID Register

Byte	5 Pin #	Name	Control Function	Type	0	1	Default
Bit 7		RID3		R			Х
Bit 6	1	RID2	REVISION ID	R	A rev = 0000		Х
Bit 5	-	RID1	REVISION ID	R	B rev	= 0001	X
Bit 4	-	RID0		R			Х
Bit 3	-	VID3		R			0
Bit 2	-	VID2	VENDOR ID	R	0001 for	IDT/ICS	0
Bit 1	-	VID1	VENDOR ID	R	0001101	101/103	0
Bit 0	-	VID0		R]		1

SMBusTable: DEVICE ID

Byte 6	Pin #	Name	Control Function	Type	0	1	Default
Bit 7	-	De	evice ID 7 (MSB)	R			1
Bit 6	-		Device ID 6	R			1
Bit 5	-		Device ID 5	R			0
Bit 4	-		Device ID 4	R	1000 io 000 do	200 is 200 decimal or C8 hex	
Bit 3	-		Device ID 3	R	1200 is 200 decimal of Co flex		1
Bit 2	-		Device ID 2	R			0
Bit 1	-		Device ID 1	R]		0
Bit 0	-		Device ID 0	R	1		0

SMBusTable: Byte Count Register

Byte 7	Pin #	Name	Control Function	Type	0	1	Default
Bit 7			Reserved				0
Bit 6	t 6 Reserved					0	
Bit 5			Reserved				0
Bit 4	-	BC4		RW			0
Bit 3	-	BC3	Writing to this register configures how	RW	Default value	is 8 hex, so 9	1
Bit 2	-	BC2		RW	bytes (0 to 8) w	vill be read back	0
Bit 1	-	BC1	many bytes will be read back.	RW	by de	efault.	0
Bit 0	_	BC0]	RW]		0

SMBusTable: Reserved Register

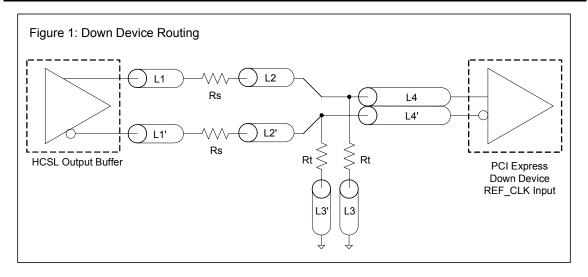
Byte 8	8 Pin #	Name	Control Function	Type	0	1	Default
Bit 7			Reserved				0
Bit 6			Reserved				0
Bit 5			Reserved				0
Bit 4			Reserved				0
Bit 3			Reserved				0
Bit 2			Reserved				0
Bit 1			Reserved				0
Bit 0			Reserved				0

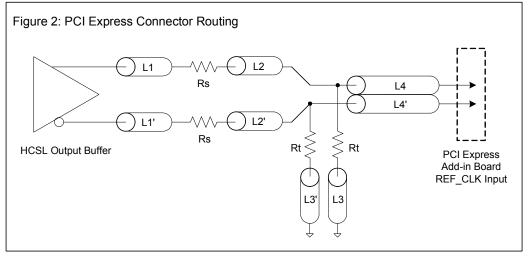


DIF Reference Clock			
Common Recommendations for Differential Routing	Dimension or Value	Unit	Figure
L1 length, route as non-coupled 50ohm trace	0.5 max	inch	1
L2 length, route as non-coupled 50ohm trace	0.2 max	inch	1
L3 length, route as non-coupled 50ohm trace	0.2 max	inch	1
Rs (100 ohm differential traces)	33	ohm	1
Rs (85 ohm differential traces)	27	ohm	1

Down Device Differential Routing			
L4 length, route as coupled microstrip 100ohm differential trace	2 min to 16 max	inch	1
L4 length, route as coupled stripline 100ohm differential trace	1.8 min to 14.4 max	inch	1

Differential Routing to PCI Express Connector			
L4 length, route as coupled microstrip 100ohm differential trace	0.25 to 14 max	inch	2
L4 length, route as coupled stripline 100ohm differential trace	0.225 min to 12.6 max	inch	2

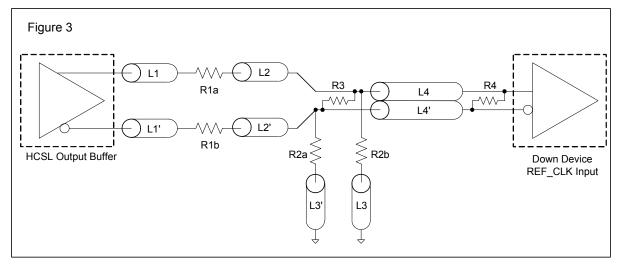




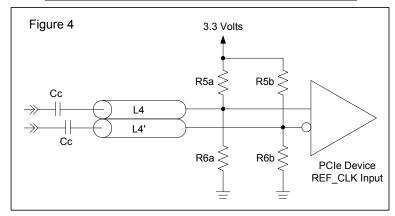


	Alternative Termination for LVDS and other Common Differential Signals (figure 3)								
Vdiff	Vp-p	Vcm	R1	R2	R3	R4	Note		
0.45v	0.22v	1.08	33	150	100	100			
0.58	0.28	0.6	33	78.7	137	100			
0.80	0.40	0.6	33	78.7	none	100	ICS874003i-02 input compatible		
0.60	0.3	1.2	33	174	140	100	Standard LVDS		

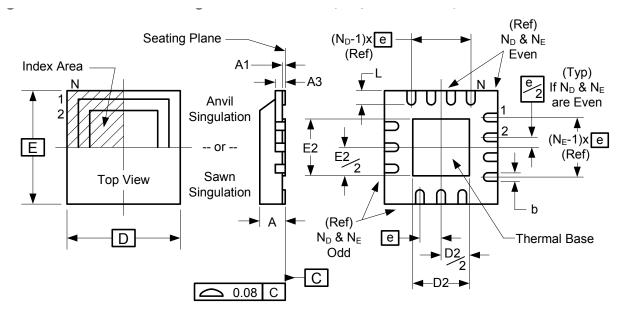
R1a = R1b = R1 R2a = R2b = R2



Cable Connected AC Coupled Application (figure 4)							
Component	Value	Note					
R5a, R5b	8.2K 5%						
R6a, R6b	1K 5%						
Cc	0.1 μF						
Vcm	0.350 volts						







Dimensi	Dimensions (mm)							
Symbol	Min	Max						
Α	0.8	1.0						
A1	0	0.05						
A3	0.25 Re	ference						
b	0.18	0.3						
е	0.50 BASIC							
D x E BASIC	8.00 >	₹8.00						
D2 MIN./MAX.	4.35	4.65						
E2 MIN./MAX.	5.05	5.35						
L MIN./MAX.	0.3	0.5						
N	56							
N_D	14							
N _E	1	4						

Ordering Information

Part / Order Number	Shipping Package	Package	Temperature	Difference	
9ZX21200AKLF	Trays	56-pin VFQFPN	0 to +70°C	W/O Byte 0 PLL Control	
9ZX21200AKLFT	Tape and Reel	56-pin VFQFPN	0 to +70°C		
9ZX21200BKLF	Trays	56-pin VFQFPN	0 to +70°C	With Byte 0 PLL Mode	
9ZX21200BKLFT	Tape and Reel	56-pin VFQFPN	0 to +70°C	Control	

[&]quot;LF" suffix to the part number designates Pb-Free configuration, RoHS compliant.

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[&]quot;A" and "B" are the device revision designators (will not correlate with the datasheet revision).



Rev.	Issue Date	Issuer	Description	Page #	
A 9/13/2011			Updated electrical tables with char data		
		2. Fixed minor typographical errors	Various		
		Moved to final			
B 12/8/2011	RDW	Added B rev functionality description to Features, Benefits			
		2. Updated tDSPO_BYP parameter from +/-350ps to +/-250ps	1,7,11,15		
		3.Updated SMBus Byte 0 with B rev functionality			
		4. Updated ordering information to include B rev			
C 4/18/2012	RDW	Updated Power Connections table to be consistent with 9ZXL1230			
		2. Updated Rp values on Output Terminations Table from 43.2 ohms to	2,8		
			42.2 or 43.2 ohms to be consistent with Intel.		
D 4/15/2013	4/15/2012	RDW	Corrected typo in OE# Latency parameter; changed 1 min. to 3 max.	5	
	אטחח	cycles to 4 min. to 12 max. clocks.	<u>ت</u>		

9ZX21200



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